

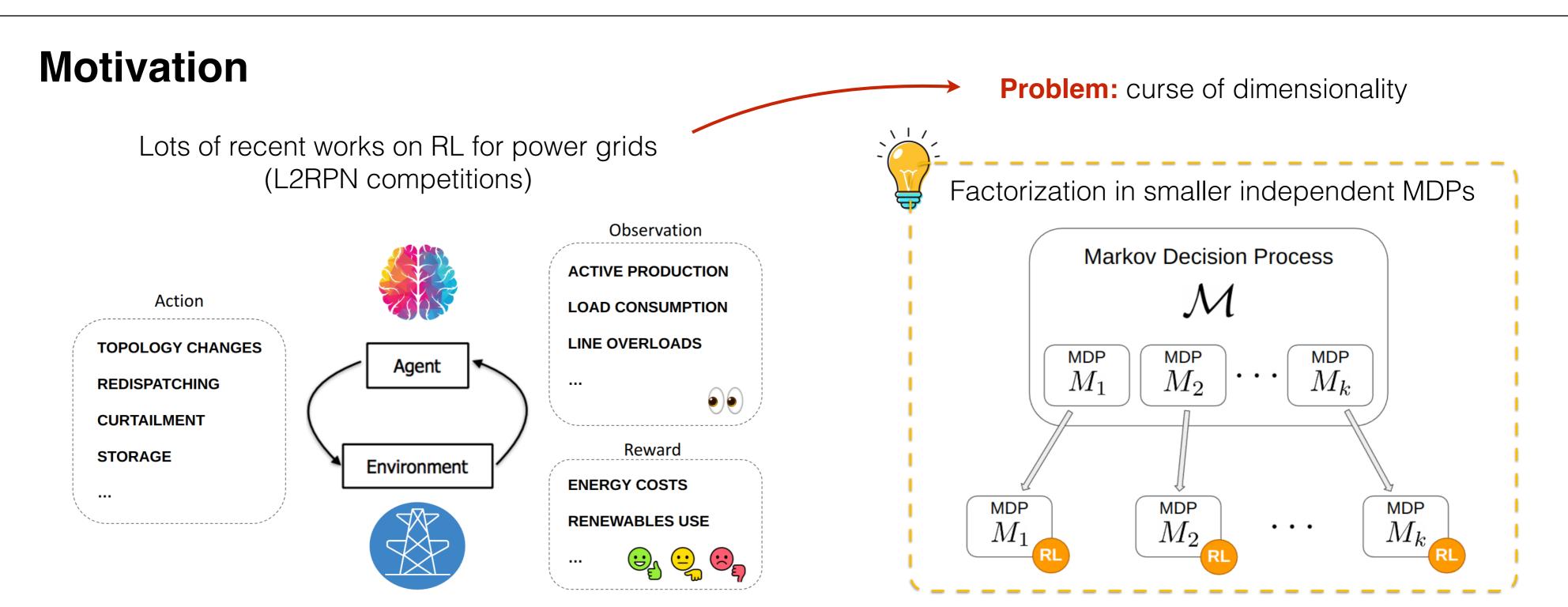




State and Action Factorization in Power Grids

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Contribution



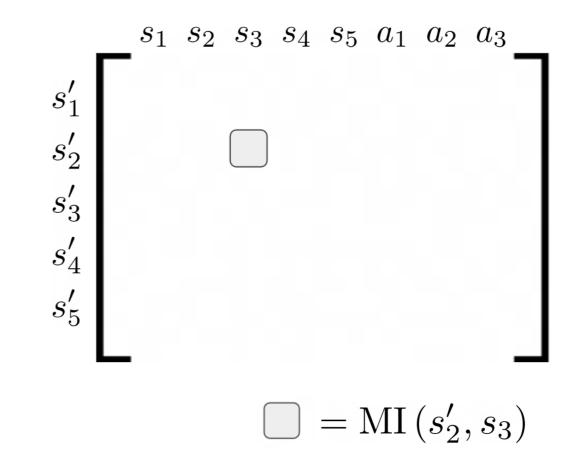
Algorithm 1: State and Actor Factorization

Input: MDP \mathcal{M} , Explorative policy π_e , Threshold δ

Output: Factorization $(\widehat{\mathcal{S}}_k, \widehat{\mathcal{A}}_k)_{k=1}^{\widehat{K}}$

Algorithm:

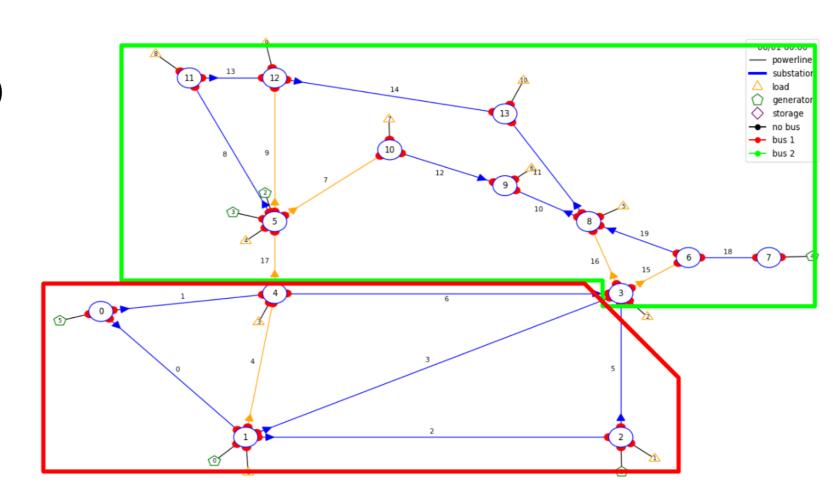
- 1. Collect a dataset \mathcal{D} of transitions from \mathcal{M} with policy π_e
- **2.** Compute the adjacency matrix $\widehat{I}_{\mathcal{G}}$ approximating the mutual information on \mathcal{D} and using δ as threshold
- **3.** Transform $\widehat{I}_{\mathcal{G}}$ into a pseudo-block diagonal matrix and define the set of clusters $(\widehat{\mathcal{S}}_k, \widehat{\mathcal{A}}_k)_{k=1}^{\widehat{K}}$ corresponding to diagonal blocks

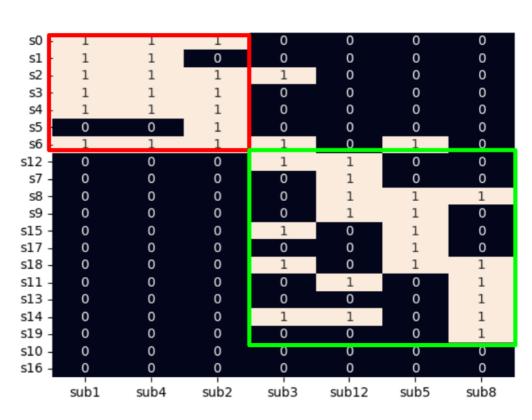


Experiments

- Synthetic data (error = 0.02)
- IEEE case14 benchmark (Grid2Op simulator)

≥ domain-expert analysis (*)





(*) Marot et al. "Guided machine learning for power grid segmentation" (2018)

Future work = {larger grids, hyperparams, correlation metrics, clustering, ... }





